Practice Problems S3

1. Determine whether the following matrices are elementary matrices or not; write down the inverses of the elementary matrices (explain your answer):

(a)
$$\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$
, (b) $\begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$, (c) $\begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$, (d) $\begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$,

(e)
$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix}, (f) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & -1 \end{bmatrix}.$$

2. Find an invertible matrix U such that the product R=UA is the reduced row-echelon form of A if

$$A = \left[\begin{array}{rrrr} 1 & -1 & 3 & 5 \\ 3 & -2 & 1 & -2 \\ -1 & 1 & 1 & 3 \end{array} \right].$$

3. Express the following matrix as a product of elementary matrices:

$$A = \left[\begin{array}{cc} 5 & 3 \\ 2 & 1 \end{array} \right].$$

- 4. Find the matrix of the reflection in the line y = -x.
- 5. Find a rotation or a reflection that is equal to
 - (a) reflection in the y-axis followed by rotation through $\pi/2$;
 - (b) rotation through $\pi/2$ followed by reflection in the line y=x.

- 6. Given $T([1 2]^T) = \begin{bmatrix} 3 & 4 \end{bmatrix}^T$ and $T([-2 & 5]^T) = \begin{bmatrix} -1 & 4 \end{bmatrix}^T$, find $T([-4 & 3]^T)$ if T is a linear transformation.
- 7. Consider a Markov chain that starts in state 1 with transition matrix $P=\begin{bmatrix}\frac{1}{3} & \frac{2}{3}\\ \frac{2}{3} & \frac{1}{3}\end{bmatrix}$.
 - (a) Explain why the chain is regular.
 - (b) Find the probability that the chain is in state 1 after 2 transitions.
 - (c) Find the steady-state vector for the chain.

Recommended Problems:

Pages 68 - 69: 1; 2a, b; 3a; 5a, b; 6 a,b; 7; 8b, c; Pages 80-81: 1. b, c; 2. a; 3, 4, 5, 9, 10, 12; Pages 101-102: 1, 2, a, c; Page 101-102: 1. a, b, f, g, h, k, l, m, n, o, p; 5. a, b; 6, 7, 8, 9, 11, 13, 14, 15;

Solutions

- 1. Exercise.
- 2. To find such an invertible matrix U that transforms A into its reduced row-echelon form R, we have to bring $[A|I_3]$ to [R|U]:

$$[A|I_3] = \begin{bmatrix} \mathbf{1} & -1 & 3 & 5 & 1 & 0 & 0 \\ 3 & -2 & 1 & -2 & 0 & 1 & 0 \\ -1 & 1 & 1 & 3 & 0 & 0 & 1 \end{bmatrix} \longrightarrow \begin{bmatrix} \mathbf{1} & -1 & 3 & 5 & 1 & 0 & 0 \\ 0 & \mathbf{1} & -8 & -17 & -3 & 1 & 0 \\ 0 & 0 & 4 & 8 & 1 & 0 & 1 \end{bmatrix}$$

(Row 2 has been replaced by row2-3xrow1, and Row 3 by r3 + r1)

$$r3 \text{ by } \frac{r3}{4} \longrightarrow \begin{bmatrix} \mathbf{1} & -1 & 3 & 5 & 1 & 0 & 0 \\ 0 & \mathbf{1} & -8 & -17 & -3 & 1 & 0 \\ 0 & 0 & \mathbf{1} & 2 & 1/4 & 0 & 1/4 \end{bmatrix}$$

 $r1 \text{ by } r1-3(r3) \text{ and } r2 \text{ by } r2+8(r3) \longrightarrow \begin{bmatrix} \mathbf{1} & -1 & 0 & -1 & 1/4 & 0 & -3/4 \\ 0 & \mathbf{1} & 0 & -1 & -1 & 1 & 2 \\ 0 & 0 & \mathbf{1} & 2 & 1/4 & 0 & 1/4 \end{bmatrix}$

$$r1 \text{ by } r1 + r2 \longrightarrow \begin{bmatrix} \mathbf{1} & 0 & 0 & -2 & -3/4 & 1 & 5/4 \\ 0 & \mathbf{1} & 0 & -1 & -1 & 1 & 2 \\ 0 & 0 & \mathbf{1} & 2 & 1/4 & 0 & 1/4 \end{bmatrix}.$$

So,
$$R = \begin{bmatrix} \mathbf{1} & 0 & 0 & -2 \\ 0 & \mathbf{1} & 0 & -1 \\ 0 & 0 & \mathbf{1} & 2 \end{bmatrix}$$
 and $U = \begin{bmatrix} -3/4 & 1 & 5/4 \\ -1 & 1 & 2 \\ 1/4 & 0 & 1/4 \end{bmatrix}$. One can

check that R = UA. Note that this invertible matrix U is not unique. It depends on the sequence of row operations performed to bring A to its reduced row-echelon form.

3. The matrix $A = \begin{bmatrix} 5 & 3 \\ 2 & 1 \end{bmatrix}$ has determinant $\det(A) = 5 \times 1 - 2 \times 3 = -1 \neq 0$. So, A is invertible. It can be carried to the identity matrix I_2 by row operations.

Step 1: Substract 2 times row 2 from row 1:

$$A = \begin{bmatrix} 5 & 3 \\ 2 & 1 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 1 \\ 2 & 1 \end{bmatrix} \quad \left(I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \longrightarrow F_1 = \begin{bmatrix} 1 & -2 \\ 0 & 1 \end{bmatrix} \right)$$

Step 2: Substract 2 times row 1 from row 2:

$$\longrightarrow \left[egin{array}{cc} 1 & 1 \ 0 & -1 \end{array}
ight] \quad \left(I_2 = \left[egin{array}{cc} 1 & 0 \ 0 & 1 \end{array}
ight] \longrightarrow F_2 = \left[egin{array}{cc} 1 & 0 \ -2 & 1 \end{array}
ight]
ight)$$

Step 3: Multiply row 2 by -1:

$$\longrightarrow \left[\begin{array}{cc} 1 & 1 \\ 0 & 1 \end{array}\right] \quad \left(I_2 = \left[\begin{array}{cc} 1 & 0 \\ 0 & 1 \end{array}\right] \longrightarrow F_3 = \left[\begin{array}{cc} 1 & 0 \\ 0 & -1 \end{array}\right]\right)$$

Step 4: Substract row 2 from row 1:

$$\longrightarrow \left[\begin{array}{cc} 1 & 0 \\ 0 & 1 \end{array}\right] \quad \left(I_2 = \left[\begin{array}{cc} 1 & 0 \\ 0 & 1 \end{array}\right] \longrightarrow F_4 = \left[\begin{array}{cc} 1 & -1 \\ 0 & 1 \end{array}\right]\right)$$

We have $A^{-1} = F_4 F_3 F_2 F_1$. Therefore, $A = E_1 E_2 E_3 E_4$, where E_1 , E_2 , E_3 and E_4 are elementary matrices given by $E_1 = F_1^{-1} = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$, $E_2 = F_2^{-1} = \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix}$, $E_3 = F_3^{-1} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$ and $E_4 = F_4^{-1} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$.

4. Denote by \vec{v}' the reflection of $\vec{v} = \begin{bmatrix} x \\ y \end{bmatrix}$ in the line y = x and \vec{v}'' the reflection of \vec{v}' in the line y = -x. We know that $\vec{v}' = \begin{bmatrix} y \\ x \end{bmatrix}$. From the figure, we see that \vec{v}'' is the reflection of \vec{v}' about the origin. Therefore, $\vec{v}'' = \begin{bmatrix} -y \\ -x \end{bmatrix}$. It follows that the reflection about the line y = -x is a linear transformation with matrix $\begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}$. It is the composition of the reflection in the line y = x with the reflection about the origin: $\begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}$.

Figure 1: Reflection of vectors of \mathbb{R}^2 about the line y = -x:

- 5. (a) The reflection of vectors of \mathbb{R}^2 in the y-axis is defined by $T([x\ y]^T) = [-x\ y]^T$ and the rotation $R_{\pi/2}$ is given by $R_{\pi/2}([x\ y]^T) = [-y\ x]$. We have: $R_{\pi/2} \circ T([x\ y]^T) = R_{\pi/2}(T([x\ y]^T)) = R_{\pi/2}([-x\ y]^T) = [-y\ -x]^T$. Therefore, the reflection in the y-axis followed by the rotation through $\pi/2$ is the reflection about the line y = x.
 - (b) $R_{\pi/2}([x\ y]^T)$ and $T([x\ y]^T) = [y\ x]^T$ is the reflection about the line y = x. We have $T \circ R_{\pi/2}([x\ y]^T) = T(R_{\pi/2}([x\ y]^T)) = T([-y\ x]^T) = [x\ -y]^T$. It is the reflection in the x-axis.
- 6. Given that $T([1 -2]^T) = [3 4]^T$ and $T([-2 5]^T) = [-1 4]^T$, $T([-4 3]^T)$ can be computed if we can express $[-4 3]^T$ as a linear combination of vectors $[1 -2]^T$ and $[-2 5]^T$, i.e.; find a and b such that $[-4 3]^T = a[1 -2]^T + b[-2 5]^T$. We have:

$$\begin{cases}
-4 &= a - 2b \\
3 &= -2a + 5b
\end{cases} \implies \begin{bmatrix}
1 & -2 \\
-2 & 5
\end{bmatrix} \begin{bmatrix}
a \\
b
\end{bmatrix} = \begin{bmatrix}
-4 \\
3
\end{bmatrix}$$

$$\implies \begin{bmatrix}
a \\
b
\end{bmatrix} = \begin{bmatrix}
1 & -2 \\
-2 & 5
\end{bmatrix}^{-1} \begin{bmatrix}
-4 \\
3
\end{bmatrix}$$

$$= \frac{1}{5 - 4} \begin{bmatrix}
5 & 2 \\
2 & 1
\end{bmatrix} \begin{bmatrix}
-4 \\
3
\end{bmatrix} = \begin{bmatrix}
-14 \\
-5
\end{bmatrix},$$

i.e., a = -14 and -5. It follows that

$$T([-4 \ 3]^T) = aT([1 \ -2]^T) + bT([-2 \ 5]^T) = -14[3 \ 4]^T - 5[-1 \ 4]^T = [-37 \ 76]^T.$$

- 7. This Markov chain with transition matrix $P = \begin{bmatrix} \frac{1}{3} & \frac{2}{3} \\ \frac{2}{3} & \frac{1}{3} \end{bmatrix}$, starting in state 1, has initial state vector $S_0 = \begin{bmatrix} 1 & 0 \end{bmatrix}$.
 - (a) Since $P^1 = P$ is the transition matrix with only nonzero entries, all powers of P also have nonzero entries. So, at least one power of P has nonzero entries, i.e., the chain is regular.
 - (b) $S_{m+1} = PS_m = P^{m+1}S_0$, where $S_0 = \begin{bmatrix} 1 & 0 \end{bmatrix}$. So, $S_1 = PS_0 = \begin{bmatrix} \frac{1}{3} & \frac{2}{3} \\ \frac{2}{3} & \frac{1}{3} \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} \frac{1}{3} \\ \frac{2}{3} \end{bmatrix}$ and the state-vector S_2 after two transitions is $S_2 = PS_1 = \begin{bmatrix} \frac{1}{3} & \frac{2}{3} \\ \frac{2}{3} & \frac{1}{3} \end{bmatrix} \begin{bmatrix} \frac{1}{3} \\ \frac{2}{3} \end{bmatrix} = \begin{bmatrix} \frac{5}{9} \\ \frac{4}{9} \end{bmatrix}$. So, the probability for the chain to be in state 1 after 2 transitions is $\frac{5}{9}$.

(c) Since the chain is regular, it has a steady state-vector which is the only probability vector S solving the homogeneous system $(I_2 - P)X = 0$.

$$I_2 - P = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} - \begin{bmatrix} \frac{2}{3} & -\frac{2}{3} \\ -\frac{2}{3} & \frac{2}{3} \end{bmatrix} = \begin{bmatrix} \frac{1}{3} & \frac{2}{3} \\ \frac{2}{3} & \frac{1}{3} \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix}$$

 $(r_1 \to 3 \times r_1/2 \text{ and } r_2 \to r_1 + r_2)$. So, the homogeneous system $(I_2 - P)X = 0$ has general solution $X = t[1 \ 1]^T$, $t \in \mathbb{R}$, In particular the steady state-vector (which is a solution to the homosyst.) has the form $S = t[1 \ 1]$, for some $t \in \mathbb{R}$. Since S is a probability vector, the sum of its entries is 1, therefore t = 1/2 and $S = \frac{1}{2}[1 \ 1]^T$.