

Department of Mathematics, and Statistics
University of Calgary

Math 311

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1. Give an example of each of the following:
 - a. A subset, U , of a vector space, V , which is **not** a subspace of the vector space, V .
 - b. A subset, B , of a vector space, V , which is not linearly independent.
 - c. A subset, B , of a vector space, V , which is linearly independent.
 - d. A mapping, T , between two vector spaces, U and V , which is a linear transformation and which is one-to-one.
 - e. A mapping, T , between two vector spaces, V and W , which is a linear transformation and which is onto.
 - f. A subset, B , of a vector space, V , consisting of at least three vectors and which is an orthogonal set and which is not an orthonormal set.
 - g. A subset, B , of a vector space, V , consisting of at least three vectors and which is an orthonormal set but is not one of the standard bases of the vector space.
 - h. A 3×3 matrix which is positive definite and which is not a diagonal matrix.
 - i. A 3×3 matrix which is not positive definite and which is not a diagonal matrix.

2. Give a definition for each of the following:
 - a. A basis of a vector space.
 - b. Dimension of a vector space
 - c. A subspace of a vector space.
 - d. Rank of an $m \times n$ matrix A .
 - e. A linear transformation, T , between the vector spaces U and V .
 - f. $\text{Ker } T$, where T is a linear transformation between vector spaces U and V .
 - g. $\text{Im } T$, where T is a linear transformation between vector spaces U and V .
 - h. A one-to-one linear transformation, T between the vector spaces U and V .
 - i. A linear transformation, T , between the vector spaces U and V which is onto.
 - j. An isomorphism T , between two vector spaces U and V .
 - k. A linearly independent set of vectors.
 - l. A linearly dependent set of vectors.
 - m. An orthogonal set of vectors.
 - n. An orthonormal set of vectors.
 - o. An eigenvalue of an $n \times n$ matrix.
 - p. An eigenvector of an $n \times n$ matrix.
 - q. An orthogonal matrix, P .
 - r. A symmetric matrix, C .
 - s. An $n \times n$ matrix A is similar to an $n \times n$ matrix B .
 - t. An $n \times n$ matrix, A , is diagonalizable.

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- u. An $n \times n$ matrix, B , is orthogonally diagonalizable.
 - v. An $n \times n$ matrix, A , is positive definite.
 - w. The rank of a linear transformation T from the vector space U to the vector space V .
3. T is a linear transformation between the vector spaces U and V .
- a. Show that $\ker T = \{ \mathbf{0} \}$ if and only if T is one-to-one.
 - b. Show that $\text{Im } T = V$ if and only if T is onto.
 - c. Show that if T is one-to-one then every set of linearly independent vectors in U is mapped to a set of linearly independent vectors in V .
4. In each case, either prove the statement or give an example in which it is false.
Throughout, let T be a linear transformation between V and W where V and W are finite dimensional vector spaces.
- a. If $V = W$, then $\ker T \subseteq \text{Im } T$.
 - b. If $\dim V = 5$, and $\dim W = 3$, and $\dim(\ker T) = 2$, then T is onto.
 - c. If $\dim V = 5$, and $\dim W = 4$, then $\ker T \neq \{ \mathbf{0} \}$
 - d. If $\ker T = V$, then $W = \{ \mathbf{0} \}$
 - e. If $W = \{ \mathbf{0} \}$, then $\ker T = V$.
 - f. If $W = V$, and $\text{Im } T \subseteq \text{Ker } T$, then $T = \mathbf{0}$.
 - g. If V has the basis $\{ e_1, e_2, e_3 \}$, and if $T(e_1) = \mathbf{0} = T(e_2)$, then $\dim(\text{im } T) \leq 1$.
 - h. If T is one-to-one, then $\dim V \leq \dim W$
 - i. If $\dim V \leq \dim W$, then T is one-to-one.
 - j. If T is onto, then $\dim V \geq \dim W$.

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- k. If $\dim V \geq \dim W$, then T is onto.
- l. If $\dim(\ker T) \leq \dim W$, then $\dim W \geq \frac{1}{2} \dim V$.
5. Find a linear transformation with the given properties:
- a. $T : \mathfrak{R}^2 \rightarrow \mathfrak{R}^3$ such that $T(1,2) = (1,0,1)$; $T(-1,0) = (0,1,1)$. Find $T(2,1)$.
- b. $T : P_2 \rightarrow P_3$ such that $T(x^2) = x^3$; $T(x+1) = 0$; $T(x-1) = x$. Find $T(x^2 + x - 1)$.
6. $T : V \rightarrow W$ is a linear transformation between vector spaces V and W . Show that $T(\mathbf{v} - \mathbf{v}_1) = T(\mathbf{v}) - T(\mathbf{v}_1)$ for all $\mathbf{v}, \mathbf{v}_1 \in V$
7. $T : V \rightarrow W$ is a linear transformation between vector spaces V and W . Show that
- a. If U is a subspace of V , then $T(U) = \{T(\bar{\mathbf{u}}) : \bar{\mathbf{u}} \in U\}$ is a subspace of W .
- b. If P is a subspace of W , then $T^{-1}(P) = \{\mathbf{v} \in V : T(\bar{\mathbf{v}}) \in P\}$ is a subspace of V .
8. Let $T : \mathfrak{R}^m \rightarrow \mathfrak{R}^n$ be a linear transformation with vectors written in rows.
- a. Show that there exists an $m \times n$ matrix A such that $T(\bar{\mathbf{x}}) = \bar{\mathbf{x}} A$ for all $\bar{\mathbf{x}} \in \mathfrak{R}^m$
- b. If $\{\bar{\mathbf{e}}_1, \dots, \bar{\mathbf{e}}_m\}$ is the standard basis for \mathfrak{R}^m , show that the rows of A are $T(\bar{\mathbf{e}}_1), T(\bar{\mathbf{e}}_2), \dots, T(\bar{\mathbf{e}}_m)$.
9. Let $T : V \rightarrow W$ be a linear transformation. Let $\mathbf{v}_1, \dots, \mathbf{v}_n \in V$.
- a. If $\{T(\bar{\mathbf{v}}_i)\}_{i=1}^n$ is linearly independent, show that $\{\bar{\mathbf{v}}_i\}_{i=1}^n$ is linearly independent.

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- b. Give an example to demonstrate that the converse of (a) is false.
10. If $T : V \rightarrow V$ is a linear transformation (usually such a linear transformation is called a linear operator) such that $T(T(\bar{v})) = \bar{v}$, for all $\bar{v} \in V$. If $\mathbf{0} \neq \bar{v} \in V$, show that $\{\bar{v}, T(\bar{v})\}$ is linearly independent if and only if $T(\bar{v}) \neq \bar{v}$ and $T(\bar{v}) \neq -\bar{v}$.
11. For any $a \in \mathfrak{R}$, define the evaluation map $E_a : P_n \rightarrow \mathfrak{R}$ by $E_a(p(x)) = p(a)$ for $p(x) \in P_n$.
- a. Show that E_a is a linear transformation which satisfies the property $E_a(x^k) = (E_a(x))^k$ for $k \in \{0, 1, 2, \dots\}$
- b. If $T : P_n \rightarrow \mathfrak{R}$ is a linear transformation which satisfies $T(x^k) = (T(x))^k$, $k \in \{0, 1, 2, \dots\}$, show that $T = E_a$ for some $a \in \mathfrak{R}$.
12. Find a basis of (1) Ker T, and (2) Im T in each case:
- a. $T : P_2 \rightarrow \mathfrak{R}^2$ such that $T(a + bx + cx^2) = (a, b)$
- b. $T : \mathfrak{R}^3 \rightarrow \mathfrak{R}^3$ such that $T(x, y, z) = (x + y, 0, x + y)$
- c. $T : M_{22} \rightarrow M_{22}$ such that $T \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} a+b & b+c \\ c+d & d+a \end{pmatrix}$
- d. $T : M_{22} \rightarrow \mathfrak{R}$ such that $T \begin{pmatrix} a & b \\ c & d \end{pmatrix} = a + d$
- e. $T : M_{22} \rightarrow M_{22}$ such that $T(X) = XA - AX$ where $A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$

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13. Let $P : V \rightarrow \mathfrak{R}$ and $Q : V \rightarrow \mathfrak{R}$ be linear transformations. Let $T : V \rightarrow \mathfrak{R}^2$ be defined by $T(\mathbf{v}) = (P(\mathbf{v}), Q(\mathbf{v}))$:

a. Show that T is a linear transformation.

b. Show that $\ker T = \ker P \cap \ker Q$

14. Use the Gram-Schmidt algorithm to convert the given basis of V into an orthogonal basis of V .

a. $V = \mathbb{R}^3$, $B = \left\{ \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix} \right\}$

b. $V = \mathbb{R}^4$, $B = \left\{ \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -2 \\ 2 \end{pmatrix} \right\}$ is a basis for a subspace of \mathbb{R}^4 and must

first be extended to a basis for \mathbb{R}^4

15. If U is a subspace of a vector space, \mathbb{R}^n , show that

a. U^\perp is a subspace of \mathbb{R}^n .

b. $U^{\perp\perp} = U$.