

SOLUTIONS to ASSIGNMENT 3.

MATH 311

FALL 2010

1. Let  $A = \begin{bmatrix} 1 & -1 & -1 & 2 & 2 & 3 \\ -2 & 2 & 3 & -6 & -3 & -11 \\ -1 & 1 & 2 & -4 & -3 & -8 \\ 0 & 0 & 1 & -2 & 1 & -5 \end{bmatrix}$ .

$$\begin{array}{cccccc} 1 & -1 & -1 & 2 & 2 & 3 \\ -2 & 2 & 3 & -6 & -3 & -11 \\ -1 & 1 & 2 & -4 & -3 & -8 \\ 0 & 0 & 1 & -2 & 1 & -5 \end{array}, \text{ row echelon form: } \begin{array}{cccccc} 1 & -1 & 0 & 0 & 0 & -2 \\ 0 & 0 & 1 & -2 & 0 & -5 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array}$$

(1) Find bases of  $\text{row}(A)$  and of  $\text{col}(A)$ , and so determine their dimensions. 4 marks

(2) Find bases of  $\text{null}(A)$  and of  $\text{im}(A)$ , and so determine their dimensions. 4 marks

**Solution.** (1). Standard Gaussian elimination gives  $A \rightarrow R$  where  $R = \begin{bmatrix} 1 & -1 & 0 & 0 & 0 & -2 \\ 0 & 0 & 1 & -2 & 0 & -5 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$  is

reduced row-echelon. So, by the Rank Theorem (Theorem 1 §5.4), the first three rows of  $R$  are a basis of  $\text{row}(A)$ , whence  $\dim[\text{row}(A)] = 2 = \text{rank}(A)$ . Moreover, the leading 1s are in columns 1, 3 and 5 of  $R$ , so columns 1, 3 and 5 of  $A$  are a basis of  $\text{col}(A)$ , again by the Rank Theorem.

(2). The reduced row echelon form of  $A$  is  $\begin{bmatrix} 1 & -1 & 0 & 0 & 0 & -2 \\ 0 & 0 & 1 & -2 & 0 & -5 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$  so the leading variables are  $x_1, x_3$  and  $x_5$ . Assigning the non-leading variables as parameters:  $x_2 = r, x_4 = s$  and  $x_6 = t$ , we solve for the leading variables:  $x_1 = r + 2t, x_3 = 2s + 5t$ , and  $x_5 = 0$ . Thus the general solution is

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{bmatrix} = rX_1 + sX_2 + tX_3 \text{ where } X_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, X_2 = \begin{bmatrix} 0 \\ 0 \\ 2 \\ 1 \\ 0 \\ 0 \end{bmatrix} \text{ and } X_3 = \begin{bmatrix} 2 \\ 0 \\ 5 \\ 0 \\ 0 \\ 1 \end{bmatrix}.$$

Then  $\{X_1, X_2, X_3\}$  is a basis of  $\text{null}(A)$  by Theorem 2 §5.4, so  $\dim[\text{null}(A)] = 3$ . Note that  $A$  is  $4 \times 6$  here with rank  $r = \dim[\text{col}(A)] = 3$  so  $\dim[\text{null}(A)] = 3 = 6 - 3 = n - r$  as Theorem 2 §5.4 asserts.

As to the image of  $A$ , we have  $\text{im}(A) = \text{col}(A)$  again by Theorem 2 §5.4, so  $\dim[\text{im}(A)] = \dim[\text{col}(A)] = 2$ , and a basis is presented in part (1).

2. Let  $\mathcal{B} = \{(2, 1, 1, -1), (1, -3, 1, 0), (-1, 3, 10, 11), (1, 0, -1, 1)\}$  in  $\mathbb{R}^4$ .

(1) Show that  $\mathcal{B}$  is a basis of  $\mathbb{R}^4$ . 4 marks

(2) Express  $X = (a, b, c, d)$  as a linear combination of the vectors in  $\mathcal{B}$ . 4 marks

**Solution.** Write  $X_1 = (2, 1, 1, -1), X_2 = (1, -3, 1, 0), X_3 = (-1, 3, 10, 11)$  and  $X_4 = (1, 0, -1, 1)$ .

(1). The set  $\mathcal{B}$  is orthogonal (for example  $X_1 \bullet X_2 = 2 - 3 + 1 + 0 = 0$  and  $X_2 \bullet X_3 = -1 - 9 + 10 + 0 = 0$ ).

Hence  $\mathcal{B}$  is independent (Theorem 5 §5.3), and so is a basis of  $\mathbb{R}^4$  (by Theorem 4 §6.4).

Since  $|\mathcal{B}| = 4$  and  $\dim(\mathbb{R}^4) = 4$ ,  $\mathcal{B}$  must be a basis of  $\mathbb{R}^4$ .

(2). The expansion theorem (Theorem 6 §5.3) gives

$$\begin{aligned} X &= \left( \frac{X \bullet X_1}{\|X_1\|^2} \right) X_1 + \left( \frac{X \bullet X_2}{\|X_2\|^2} \right) X_2 + \left( \frac{X \bullet X_3}{\|X_3\|^2} \right) X_3 + \left( \frac{X \bullet X_4}{\|X_4\|^2} \right) X_4 \\ &= \left( \frac{2a+b+c-d}{7} \right) X_1 + \left( \frac{a-3b+c}{11} \right) X_2 + \left( \frac{-a+3b+10c+11d}{231} \right) X_3 + \left( \frac{a-c+d}{3} \right) X_4 \end{aligned}$$

3. Let  $A$  be an  $m \times n$  matrix with  $\text{rank}(A) = n$ . If the columns of  $A$  are  $C_1, C_2, \dots, C_n$ , show that  $\mathcal{B} = \{A^T C_1, A^T C_2, \dots, A^T C_n\}$  is a basis of  $\mathbb{R}^n$ . 8 marks

**Solution.** The matrix  $A^T A$  is invertible by Theorem 3 §5.4. If we write  $A = [C_1 \ C_2 \ \dots \ C_n]$  in terms of its columns, then

$$A^T A = A^T [C_1 \ C_2 \ \dots \ C_n] = [A^T C_1 \ A^T C_2 \ \dots \ A^T C_n].$$

Thus  $\mathcal{B}$  consists of the columns of the invertible matrix  $A^T A$ . By Theorem 3 §5.3,  $\mathcal{B}$  is a basis of  $\mathbb{R}^n$ .

4. Let  $A$  and  $B$  denote  $n \times n$  matrices. Write  $A \sim B$  to mean that  $A$  is similar to  $B$ .
- (1) If  $A$  is invertible, show that  $AB \sim BA$ . 2 marks
- (2) Let  $A = rI_n$  where  $r \in \mathbb{R}$ . If  $B \sim A$ , show that  $B = A$ . 3 marks
- (3) If  $A \sim B$  and  $A^3 = A$ , show that  $B^3 = B$ . 3 marks

**Solution.** (1).  $A^{-1}(AB)A = BA$ .

(2). Let  $B = P^{-1}AP$  where  $P$  is invertible. Then  $B = P^{-1}(rI_n)P = rP^{-1}P = rI_n = A$ .

(3). Let  $B = P^{-1}AP$  where  $P$  is invertible. Then

$$B^3 = (P^{-1}AP)(P^{-1}AP)(P^{-1}AP) = P^{-1}AI_nAI_nAP = P^{-1}A^3P = P^{-1}AP = B.$$

5. Let  $A$  be an  $n \times n$  diagonalizable matrix with eigenvalues  $\lambda_1, \lambda_2, \dots, \lambda_n$  (including multiplicities).
- (1) Show that  $\det(A) = \lambda_1 \lambda_2 \dots \lambda_n$ . 4 marks
- (2) Show that  $\text{tr}(A) = \lambda_1 + \lambda_2 + \dots + \lambda_n$  (where  $\text{tr}(A)$  denotes the trace of  $A$ ). 4 marks

**Solution.** Since  $A$  is diagonalizable, there is an invertible matrix  $P$  such that  $P^{-1}AP = D$  is diagonal. Moreover,  $D = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$  is the diagonal matrix with the  $\lambda_i$  down the main diagonal and zeros elsewhere.

(1). We have  $\det(P^{-1}AP) = \frac{1}{\det(P)} \det(A) \det(P) = \det(A)$ . That is  $\det(A) = \det(D) = \lambda_1 \lambda_2 \dots \lambda_n$ .

(2). Using Lemma 1 §5.5, we have  $\text{tr}(P^{-1}AP) = \text{tr}[P^{-1}(AP)] = \text{tr}[(AP)P^{-1}] = \text{tr}(A)$ .

Thus  $\text{tr}(A) = \text{tr}(D) = \lambda_1 + \lambda_2 + \dots + \lambda_n$ .

Total: 40 marks